

CSE 520

Computer Architecture II

Influence of Technology and Software on
Instruction Sets

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And then there was IBM

- Users stopped building their own machines
- IBM 701
 - 30 machines were sold in 1953-54
- IBM 650
 - A cheaper, drum based machine, more than 120 were sold in 1954 and there were orders for 750 more!
- Why was IBM late getting into computers?
 - IBM was making too much money!
 - Even without computers, IBM revenues were doubling every 4 to 5 years in 40's and 50's

Computers in mid 50' s

- Hardware was expensive
- Stores were small (1000 words)
 - No resident system-software!
- Memory access time was 10 to 50 times slower than the processor cycle
 - Instruction execution time was totally dominated by the memory reference time

Computers in mid 50' s

- The ability to design complex control circuits to execute an instruction was the central design concern as opposed to the speed of decoding or an ALU operation
- Programmer's view of the machine was inseparable from the actual hardware implementation

Earliest Instruction Sets

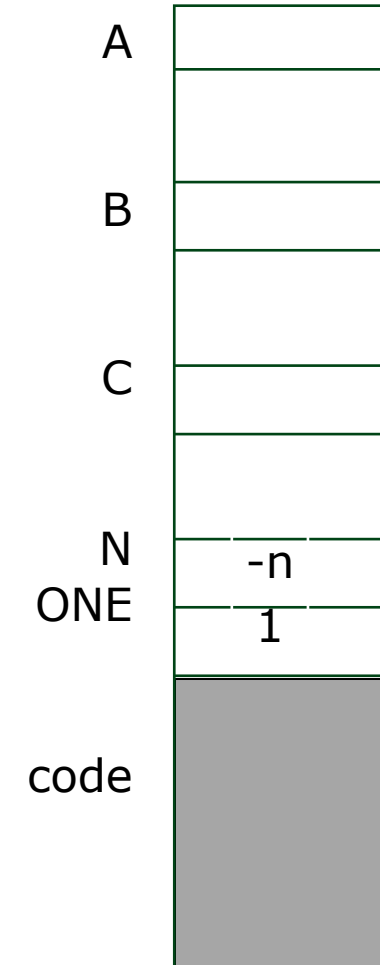
- Burks, Goldstein & von Neumann ~1946
- Single Accumulator - A carry-over from calculators.
- Typically, less than 2 dozen instructions!

LOAD	x	$AC \leftarrow M[x]$
STORE	x	$M[x] \leftarrow (AC)$
ADD	x	$AC \leftarrow (AC) + M[x]$
SUB	x	
MUL	x	Involved a quotient register
DIV	x	
SHIFT LEFT		$AC \leftarrow 2 \times (AC)$
SHIFT RIGHT		
JUMP	x	$PC \leftarrow x$
JGE	x	if $(AC) \geq 0$ then $PC \leftarrow x$
LOAD ADR	x	$AC \leftarrow \text{Extract address field}(M[x])$
STORE ADR	x	

Single Accumulator Machine

$$C_i \leftarrow A_i + B_i, \quad 1 \leq i \leq n$$

LOOP	LOAD	N
	JGE	DONE
	ADD	ONE
	STORE	N
F1	LOAD	A
F2	ADD	B
F3	STORE	C
	JUMP	LOOP
DONE	HLT	



How to modify the addresses A, B and C ?

Self-Modifying Code

- Modify the program for the next iteration

LOOP	LOAD	N
	JGE	
	DONE	
	ADD	ONE
	STORE	N
F1	LOAD	A
F2	ADD	B
F3	STORE	C
	JUMP	
	LOOP	
DONE	HLT	

LOAD	ADR	F1
	ADD	ONE
STORE	ADR	F1
LOAD	ADR	F2
	ADD	ONE
STORE	ADR	F2
LOAD	ADR	F3
	ADD	ONE
STORE	ADR	F3

Self-Modifying Code

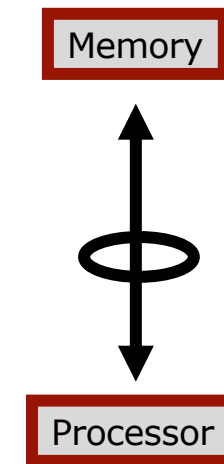
- Most of the executed instructions are for book keeping!
- Each iteration involves

	total	book-keeping
■ Instruction fetches	17	14
■ Operand fetches	10	8
■ Stores	5	4

$$C_i \leftarrow A_i + B_i, \quad 1 \leq i \leq n$$

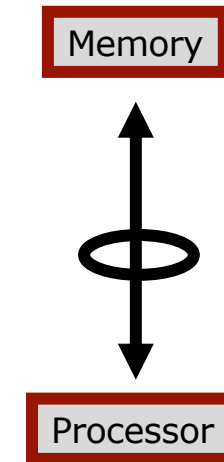
Processor-Memory Bottleneck

- Early Solutions
 - Fast local storage in the processor
 - 8-16 registers as opposed to one accumulator
 - to save on loads/stores
 - Indexing capability
 - to reduce book keeping instructions
 - Complex instructions
 - to reduce instruction fetches



Processor-Memory Bottleneck

- Early Solutions
 - Compact instructions
 - implicit address bits for operands
 - to reduce instruction fetch cost



Processor State

- The information held in the processor at the end of an instruction to provide the processing context for the next instruction.
 - Program Counter, Accumulator, . . .
- Programmer visible state of the processor (and memory) plays a central role in computer organization for both hardware and software:
 - Software must make efficient use of it
 - If the processing of an instruction can be interrupted then the hardware must save and restore the state in a transparent manner
- Programmer's machine model is a contract between the hardware and software

Processor State

- Programmer's machine model is a contract between the hardware and software

Index Registers

- Tom Kilburn, Manchester University, mid 50's
 - One or more specialized registers to simplify address calculation
 - Modify existing instructions
 - `LOAD x, IX` $AC \leftarrow M[x + (IX)]$
 - `ADD x, IX` $AC \leftarrow (AC) + M[x + (IX)]$
 - ...
 - Add new instructions to manipulate index registers
 - `JZi x, IX` if $(IX)=0$ then $PC \leftarrow x$
 else $IX \leftarrow (IX) + 1$

Index registers have accumulator-like characteristics

Using Index Registers

- Program does not modify itself
- Efficiency has improved dramatically (ops / iter)

	with index regs	without index regs
■ instruction fetch	(2)	17 (14)
■ operand fetch	2	10 (8)
■ store	2	5 (4)

- Costs:

- Complex control
- Need to operate on index registers (ALU-like circuitry)

$$C_i \leftarrow A_i + B_i, \quad 1 \leq i \leq n$$

- - 1 to 2 bits longer Instructions

Indexing vs. Index Registers

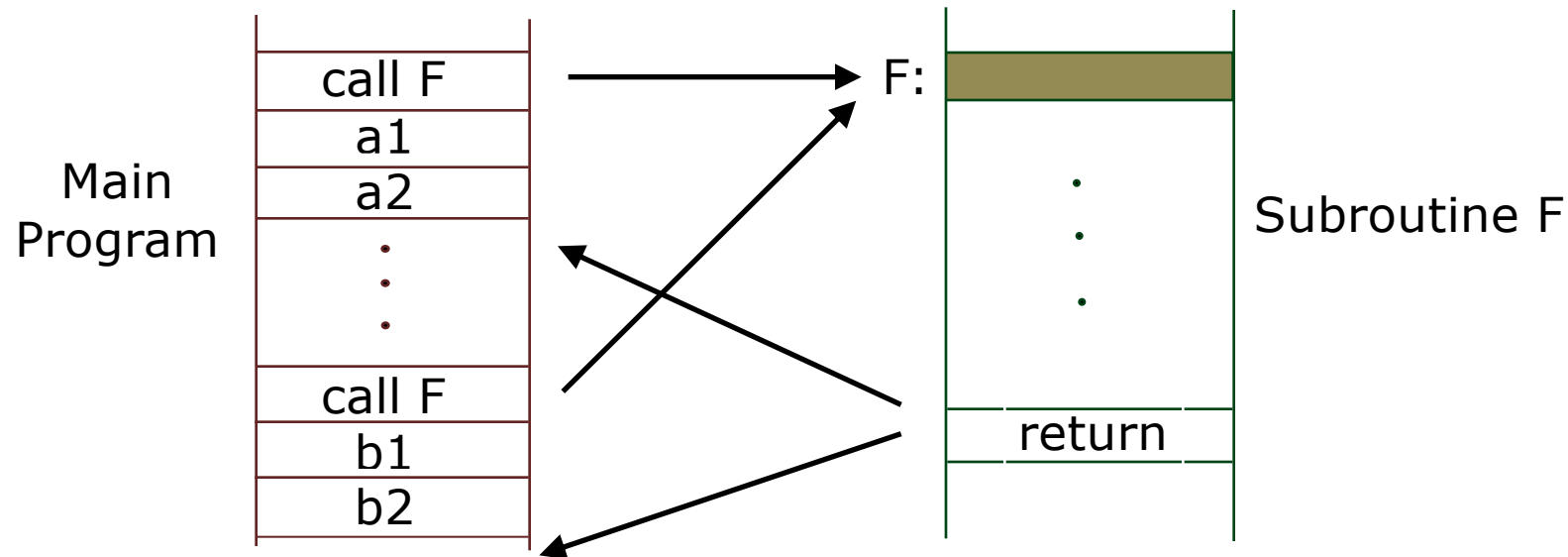
- Suppose instead of registers, memory locations are used to implement index registers.
 - ▶ `LOAD x, IX`
- Arithmetic operations on index registers can be performed by bringing the contents to the accumulator
- Most bookkeeping instructions will be avoided, but:
 - Each instruction will implicitly cause more fetches and stores
 - Complex control circuitry

Operations on Index Registers

- To increment index register by k
 - $AC < (IX)$ new instruction
 - $AC < (AC) + k$
 - $IX < (AC)$ new instruction
- Also the AC must be saved and restored
- It may be better to increment IX directly
 - $INCi \quad k, IX \quad IX \leftarrow (IX) + k$
- More instructions to manipulate index register
 - $STOREix, IX \quad M[x] \leftarrow (IX)$ (extended to fit a word)
- IX begins to look like an accumulator

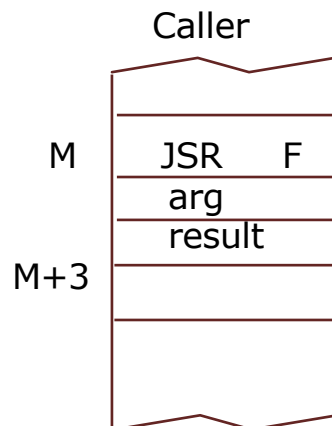
Support for Subroutine

- A special subroutine jump instruction
 - M: JSR F $F \leftarrow M + 1$ and jump to F+1



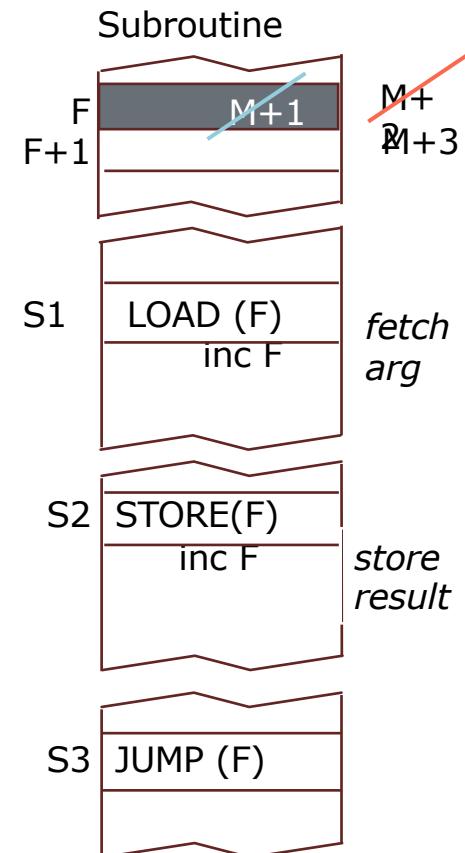
Indirect Addressing

- Indirect addressing almost eliminates the need to write self-modifying code (location F still needs to be modified)
- Indirect addressing
 - `LOAD (x)` means $AC \leftarrow M[M[x]]$



Events:

Execute M
Execute S1
Execute S2
Execute S3

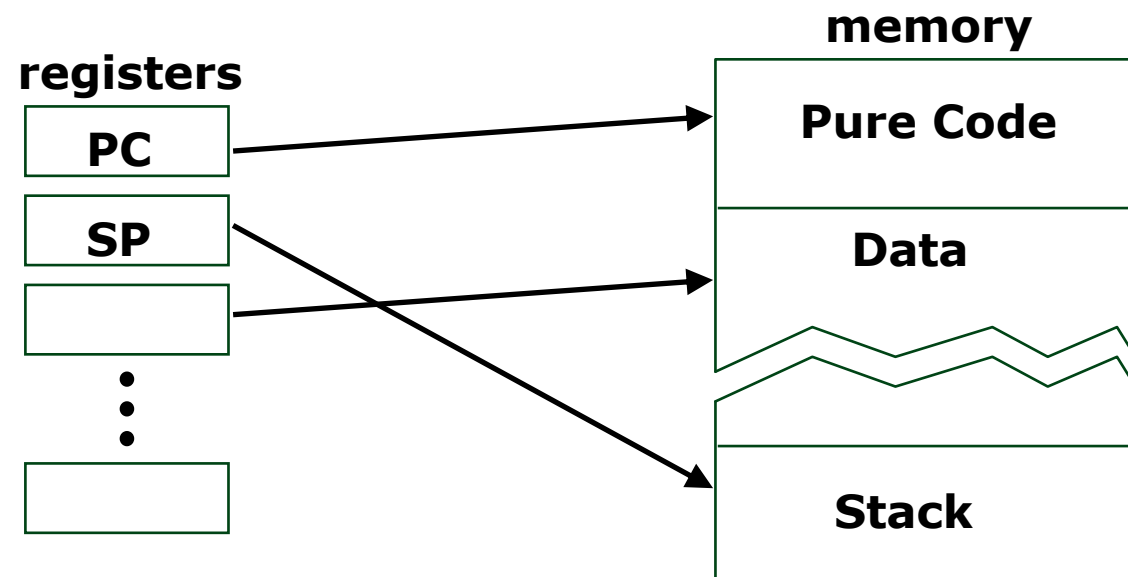


Recursive Procedure Calls

- Indirect Addressing through a register

LOAD $R_1, (R_2)$

- Load register R_1 with the contents of the word whose address is contained in register R_2



Evolution of Addressing Modes

1. Single accumulator, absolute address

LOAD x

2. Single accumulator, index registers

LOAD x, IX

3. Indirection

LOAD (x)

4. Multiple accumulators, index registers, indirection

LOAD R, IX, x

or LOAD R, IX, (x)

The meaning?

$R \leftarrow M[M[x] + (IX)]$

or $R \leftarrow M[M[x + (IX)]]$

5. Indirect through registers

LOAD $R_I, (R_J)$

6. The works

LOAD $R_I, R_J, (R_K)$

$R_J = \text{index}, R_K = \text{base addr}$

Variety of Instruction Formats

- Three address formats: One destination and up to two operand sources per instruction

(Reg x Reg) to Reg $RI \leftarrow (RJ) + (RK)$

(Reg x Mem) to Reg $RI \leftarrow (RJ) + M[x]$

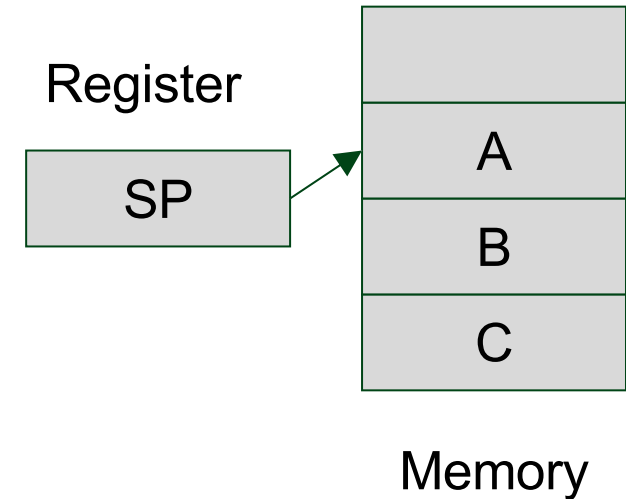
- x can be specified directly or via a register
 - Effective address calculation for x could include indexing, indirection, ...
- Two address formats: the destination is same as one of the operand sources

(Reg x Reg) to Reg $RI \leftarrow (RI) + (RJ)$

(Reg x Mem) to Reg $RI \leftarrow (RI) + M[x]$

More Instruction Formats

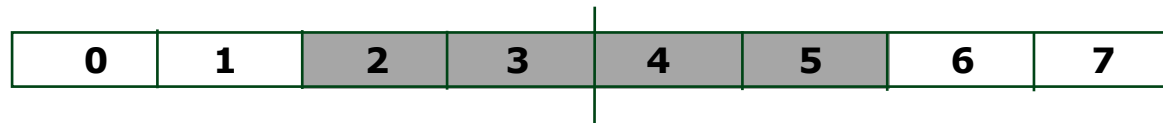
- One address formats: Accumulator machines
 - Accumulator is always other implicit operand
- Zero address formats: operands on a stack
 - $\text{add } M[\text{sp}-1] \leftarrow M[\text{sp}] + M[\text{sp}-1]$
 - $\text{load } M[\text{sp}] \leftarrow M[M[\text{sp}]]$
 - Stack can be in registers or in memory
 - Usually top of stack cached in registers



Data Formats and Addresses

- Data formats:
 - Bytes, Half words, words and double words
- Some issues
 - Byte addressing
 - Big Endian vs. Little Endian
 - Word alignment
 - Suppose the memory is organized in 32-bit words
 - Can a word address begin only at 0, 4, 8, ?

0	1	2	3
3	2	1	0



Some Problems

- Should all addressing modes be provided for every operand?
 - Regular vs. irregular instruction formats
- Separate instructions to manipulate Accumulators, Index registers, Base registers
 - Large number of instructions
- Instructions contained implicit memory references -- several contained more than one
 - Very complex control

Next Lecture Module

- Intel Pin introduction